

Tutorial 9:
Normalization Factors for *Prior*
Error Correlations

Prior Error Covariance Modeling

Recall: $\mathbf{B}_x = \mathbf{K}_b \Sigma \mathbf{C} \Sigma^T \mathbf{K}_b^T$

C is a correlation matrix for the unbalanced increments, and is modeled as the solution of a diffusion equation:

$$\partial \mathbf{x} / \partial t - \kappa \nabla^2 \mathbf{x} = 0 \quad \rightarrow \quad \mathbf{C}' \mathbf{x}$$

But, \mathbf{C}' is arbitrary at this stage, and must to be normalized to ensure that the range is ± 1 as required for a correlation function. Therefore we define:

$$\mathbf{C} = \Lambda \mathbf{C}' \Lambda^T$$

where Λ is a diagonal matrix with elements $(c'_{ii})^{-1/2}$

Finally: $\mathbf{B}_x = \mathbf{K}_b \Sigma \Lambda \mathbf{C}' \Lambda^T \Sigma^T \mathbf{K}_b^T$

Computing Λ (define NORMALIZATION)

Following Weaver & Courtier (2001) we employ two methods for computing the elements of Λ :

(i) Exact method (Nmethod=0):

$$C'e_i \rightarrow i^{th} \text{ column of } C'; \text{ save } c_{ij}$$

where $e_i^T = (0, 0, \dots, 0, 1, 0, \dots, 0)$

\uparrow
 i^{th} element

Requires N_{grid} runs of diffusion operators:
impractical for v. large grids.

Computing Λ

(ii) Randomization method (Nmethod=1):

Estimate the diagonal elements c'_{ii} of \mathbf{C}' from:

$$\mathbf{C}' \approx \frac{1}{M} \sum_{i=1}^M \xi \mathbf{C}' \xi^T = \tilde{\mathbf{C}}$$

where ξ is a random vector: $\xi \rightarrow N(\mathbf{0}, \mathbf{I})$

M is the sample size. As $M \rightarrow \infty$, $\tilde{\mathbf{C}} \rightarrow \mathbf{C}'$
(Nrandom)

Uncertainty in elements of Λ^{-1} : $(2M)^{-1/2}$

Practical requirement: $M \ll N_{grid}$

(Fisher and Courtier, 1995)

Computing Λ

Practicalities:

- choose M and run normalization driver
- choose another seed and run again
- compare the estimates – are they similar
- compute means of the two M samples
- repeat as necessary until mean does not change significantly

Normalization Tutorial Wiki Page

The screenshot shows a Mozilla Firefox browser window with the address bar displaying `https://www.myroms.org/wiki/index.php/4DVar_Normalization_Tutorial`. The page title is "4DVar Normalization Tutorial - WikiROMS". The browser's address bar shows the URL and search engines like Google. The page content includes a "WikiROMS" logo, a navigation menu, a search box, and a toolbox. The main content area features a "Tutorial Menu" and a "Contents" section. The "Introduction" section is visible at the bottom of the page.

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Introduction [edit]

In this tutorial you will compute the 4D-Var error covariance (**D**) normalization factors for the California Current System application WC13.

The error covariance matrix, $\mathbf{D} = \text{diag}(\mathbf{B}_x, \mathbf{B}_b, \mathbf{B}_f, \mathbf{Q})$, is very large and not well known. **B** and **Q** are modeled as the solution of a diffusion equation following Weaver and Courtier (2001) methodology. Each covariance matrix is factorized as $\mathbf{B} = \mathbf{K} \mathbf{\Sigma} \mathbf{C} \mathbf{\Sigma}^T \mathbf{K}^T$, where **C** is a univariate correlation matrix, **Σ** is a diagonal matrix of error standard deviations, and **K** is a multivariate balance operator. The normalization coefficients are needed to ensure that the diagonal elements of the associated correlation matrix **C** are equal to unity.

There are two methods to compute the error covariance normalization coefficients: **exact** and **randomization** (an

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WC13 C-preprocessing Options

(Basic Configuration)

Momentum Equations Options:

#define UV_ADV including advection terms
#define UV_COR including Coriolis term
#define DJ_GRADPS splines density Jacobian PGF
#define UV_QDRAG quadratic bottom friction
#define UV_VIS2 harmonic horizontal mixing
#define MIX_S_UV mixing along s-levels

Tracers Equations Options:

#define TS_U3HADVECTION 3rd-order Upstream H. advection
#define TS_C4VADVECTION 4th-order Centered V. advection
#define TS_DIF2 harmonic horizontal mixing
#define MIX_GEO_TS mixing along geo-potentials
#define SALINITY including salinity
#define NONLIN_EOS nonlinear equation of state

#define ANA_BTFLUX analytical bottom Temp flux
#define ANA_BSFLUX analytical bottom Salt flux

Vertical Turbulent Mixing Parameterization:

#define GLS_MIXING Generic Length Scale Mixing
#ifdef GLS_MIXING (K-omega)
#define N2S2_HORAVG smoothing of buoyancy/shear
#define KANTHA_CLAYSON stability function
#endif

Atmospheric Boundary Layer Parameterization:

#define BULK_FLUXES Air/sea COARE bulk fluxes

#define DIURNAL_SRFLUX imposing local diurnal cycle
#define SOLAR_SOURCE solar radiation source term
#define LONGWAVE_OUT compute outgoing long wave rad
#define EMISUSP compute E-P

Model Configuration Options:

#define SOLVE3D solve 3D primitive equations
#define CURVGRID curvilinear grid
#define MASKING land/sea masking
#define SPHERICAL spherical grid
#define PROFILE time profiling

#define SPLINES parabolic splines
reconstruction

Lateral Boundary Conditions:

#define EASTERN_WALL closed eastern wall condition

#define WEST_FSCHAPMAN free-surface, Chapman
#define WEST_M2FLATHER 2D momentum, Flather
#define WEST_M3CLAMPED 3D momentum, clamped
#define WEST_TCLAMPED tracers, clamped condition

#define NORTH_FSCHAPMAN free-surface, Chapman
#define NORTH_M2FLATHER 2D momentum, Flather
#define NORTH_M3CLAMPED 3D momentum, clamped
#define NORTH_TCLAMPED tracers, clamped

#define SOUTH_FSCHAPMAN free-surface, Chapman
#define SOUTH_M2FLATHER 2D momentum, Flather
#define SOUTH_M3CLAMPED 3D momentum, clamped
#define SOUTH_TCLAMPED tracer, clamped

#define SPONGE enhanced viscosity/diffusion areas

WC13 C-preprocessing Options (Error Covariance Normalization)

Algorithm:

#define Normalization compute 4D-Var error covariance normalization coefficients

Control Vector:

#define ADJUST_BOUNDARY open boundary conditions increments
#define ADJUST_STFLUX surface tracer flux increments
#define ADJUST_WSTRESS surface wind stress increments

Error Covariance Modeling:

#define CORRELATION model error covariance correlation with diffusion operators
#define FULL_GRID consider both interior and boundary points
#define VCONVOLUTION Vertical correlation modeling
#define IMPLICIT_VCON Implicit vertical diffusion operator
#define BALANCE_OPERATOR Multivariate balance constraint
#ifdef BALANCE_OPERATOR
#define ZETA_ELLIPTIC SSH elliptic equation method
#endif

Prior:

#define FORWARD_READ read basic state linearization in TLM and ADM files
#define FORWARD_WRITE writing basic state by the NLM
#define FORWARD_MIXING processing basic state vertical mixing coefficients
#define NL_BULK_FLUXES surface kinematic fluxes from nonlinear model

I/O :

#define OUT_DOUBLE double precision data in output NLM, TLM, RPM, and ADM

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Include File: wc13.h

```
/*
** svn $Id: wc13.h 476 2010-06-26 20:25:30Z arango $
*****
** Copyright (c) 2002-2010 The ROMS/TOMS Group                                     **
** Licensed under a MIT/X style license                                           **
** See License_ROMS.txt                                                            **
*****
**
** Options for the California Current System, 1/3 degree resolution.
**
** Application flag:      WC13
** Input script:         ocean_wc13.in
**                       s4dvar.in
**
** Available Drivers options: choose only one and activate it in the
**                           build.sh script (MY_CPP_FLAGS definition)
**
** AD_SENSITIVITY        Adjoint Sensitivity Driver
** AFT_EIGENMODES        Adjoint Finite Time Eigenmodes
** ARRAY_MODES           Stabilized representer matrix array modes
** CLIPPING              Stabilized representer matrix clipped analysis
** CORRELATION           Background-error Correlation Check
** GRADIENT_CHECK        TLM/ADM Gradient Check
** FORCING_SV           Forcing Singular Vectors
** FT_EIGENMODES        Finite Time Eigenmodes
** IS4DVAR              Incremental, strong constraint 4DVAR
** NLM_DRIVER            Nonlinear Basic State trajectory
** OPT_PERTURBATION      Optimal perturbations
** PICARD_TEST          Picard Iterations Test
** R_SYMMETRY           Representer Matrix Symmetry Test
** SANITY_CHECK         Sanity Check
** SO_SEMI              Stochastic Optimals: Semi-norm
```

4D-Var Error Covariance Normalization Files

- Four different error covariance normalization coefficients NetCDF files are required in ROMS 4D-Var algorithms to ensure that the diagonal elements of the associated correlation matrix (**C**) are equal to unity:
 - Model error normalization file, if weak constraint
 - Initial conditions normalization file
 - Open boundary conditions normalization file, if **ADJUST_BOUNDARY**
 - Surface forcing normalization file, if **ADJUST_WSTRESS** and/or **ADJUST_STFLUX**
- These normalization NetCDF files are specified in 4D-Var input script as:

NRMnameM == **../Data/wc13_nrm_m.nc**

NRMnameI == **../Data/wc13_nrm_i.nc**

NRMnameB == **../Data/wc13_nrm_b.nc**

NRMnameF == **../Data/wc13_nrm_f.nc**

Model Error and Initial Conditions Metadata

Variables:

...

```
double zeta(ocean_time, eta_rho, xi_rho) ;
    zeta:long_name = "free-surface, initial conditions error covariance normalization" ;
    zeta:units = "meter" ;
    zeta:time = "ocean_time" ;
    zeta:coordinates = "lon_rho lat_rho ocean_time" ;
double ubar(ocean_time, eta_u, xi_u) ;
    ubar:long_name = "vertically integrated u-momentum component, initial conditions error covariance normalization" ;
    ubar:units = "meter" ;
    ubar:time = "ocean_time" ;
    ubar:coordinates = "lon_u lat_u ocean_time" ;
double vbar(ocean_time, eta_v, xi_v) ;
    vbar:long_name = "vertically integrated v-momentum component, initial conditions error covariance normalization" ;
    vbar:units = "meter" ;
    vbar:time = "ocean_time" ;
    vbar:coordinates = "lon_v lat_v ocean_time" ;
double u(ocean_time, s_rho, eta_u, xi_u) ;
    u:long_name = "u-momentum component, initial conditions error covariance normalization" ;
    u:units = "meter" ;
    u:time = "ocean_time" ;
    u:coordinates = "lon_u lat_u s_rho ocean_time" ;
double v(ocean_time, s_rho, eta_v, xi_v) ;
    v:long_name = "v-momentum component, initial conditions error covariance normalization" ;
    v:units = "meter" ;
    v:time = "ocean_time" ;
    v:coordinates = "lon_v lat_v s_rho ocean_time" ;
double temp(ocean_time, s_rho, eta_rho, xi_rho) ;
    temp:long_name = "potential temperature, initial conditions error covariance normalization" ;
    temp:units = "meter" ;
    temp:time = "ocean_time" ;
    temp:coordinates = "lon_rho lat_rho s_rho ocean_time" ;
double salt(ocean_time, s_rho, eta_rho, xi_rho) ;
    salt:long_name = "salinity, initial conditions error covariance normalization" ;
    salt:units = "meter" ;
    salt:time = "ocean_time" ;
    salt:coordinates = "lon_rho lat_rho s_rho ocean_time" ;
```

Open Boundary Conditions Metadata

di mensi ons:

```
xi_rho = 56 ;  
eta_rho = 55 ;  
.  
.  
.  
lorJ = 56 ;  
boundary = 4 ;
```

vari ables:

```
double zeta_obc(ocean_time, boundary, lorJ) ;  
    zeta_obc:long_name = "free-surface, open boundaries conditions error covariance normalization" ;  
    zeta_obc:units = "meter" ;  
    zeta_obc:time = "ocean_time" ;  
double ubar_obc(ocean_time, boundary, lorJ) ;  
    ubar_obc:long_name = "vertically integrated u-momentum component, open boundaries conditions error covariance normalization" ;  
    ubar_obc:units = "meter second-1" ;  
    ubar_obc:time = "ocean_time" ;  
double vbar_obc(ocean_time, boundary, lorJ) ;  
    vbar_obc:long_name = "vertically integrated v-momentum component, open boundaries conditions error covariance normalization" ;  
    vbar_obc:units = "meter second-1" ;  
    vbar_obc:time = "ocean_time" ;  
double u_obc(ocean_time, s_rho, boundary, lorJ) ;  
    u_obc:long_name = "u-momentum component, open boundaries conditions error covariance normalization" ;  
    u_obc:units = "meter second-1" ;  
    u_obc:time = "ocean_time" ;  
double v_obc(ocean_time, s_rho, boundary, lorJ) ;  
    v_obc:long_name = "v-momentum component, open boundaries conditions error covariance normalization" ;  
    v_obc:units = "meter second-1" ;  
    v_obc:time = "ocean_time" ;  
double temp_obc(ocean_time, s_rho, boundary, lorJ) ;  
    temp_obc:long_name = "potential temperature, open boundaries conditions error covariance normalization" ;  
    temp_obc:units = "Cel si us" ;  
    temp_obc:time = "ocean_time" ;  
double sal t_obc(ocean_time, s_rho, boundary, lorJ) ;  
    sal t_obc:long_name = "sal ini ty, open boundaries conditions error covariance normalization" ;  
    sal t_obc:time = "ocean_time" ;
```

// global attri butes:

```
.: boundary_index = "West=1, South=2, East=3, North=4"
```

Surface Forcing Metadata

di mensi ons:

```
xi_rho = 56 ;  
xi_u = 55 ;  
xi_v = 56 ;  
eta_rho = 55 ;  
eta_u = 55 ;  
eta_v = 54 ;  
s_rho = 30 ;  
ocean_time = UNLIMITED ; // (1 currently)
```

vari ables:

...

```
double sustr(ocean_time, eta_u, xi_u) ;  
  sustr:long_name = "surface u-momentum stress, error covariance normalization" ;  
  sustr:units = "newton meter-2" ;  
  sustr:time = "ocean_time" ;  
  sustr:coordinates = "lon_u lat_u ocean_time" ;  
double svstr(ocean_time, eta_v, xi_v) ;  
  svstr:long_name = "surface v-momentum stress, error covariance normalization" ;  
  svstr:units = "newton meter-2" ;  
  svstr:time = "ocean_time" ;  
  svstr:coordinates = "lon_v lat_v ocean_time" ;  
double shflux(ocean_time, eta_rho, xi_rho) ;  
  shflux:long_name = "surface net heat flux, error covariance normalization" ;  
  shflux:units = "watt meter-2" ;  
  shflux:negative = "upward flux, cooling" ;  
  shflux:positive = "downward flux, heating" ;  
  shflux:time = "ocean_time" ;  
  shflux:coordinates = "lon_rho lat_rho ocean_time" ;  
double ssflux(ocean_time, eta_rho, xi_rho) ;  
  ssflux:long_name = "surface net salt flux (E-P)*SALT, error covariance normalization" ;  
  ssflux:units = "meter second-1" ;  
  ssflux:time = "ocean_time" ;  
  ssflux:coordinates = "lon_rho lat_rho ocean_time" ;
```

// global attributes:

```
:type = "ROMS/TOMS 4D-Var surface forcing error covariance normalization" ;  
:title = "California Current System, 1/3 degree resolution (WC13)" ;  
:Conventions = "CF-1.4" ;  
:grid_file = "test/WC13/Data/wc13_grd.nc" ;
```

Standard Input File: ocean_wc13.in

```
!  
! ROMS/TOMS Standard Input parameters.  
!  
!svn $Id: ocean_wc13.in 476 2010-06-26 20:25:30Z arango $  
!===== Hernan G. Arango ===  
! Copyright (c) 2002-2010 The ROMS/TOMS Group !  
! Licensed under a MIT/X style license !  
! See License_ROMS.txt !  
!===== !  
!  
! Input parameters can be entered in ANY order, provided that the parameter !  
! KEYWORD (usually, upper case) is typed correctly followed by "=" or "==" !  
! symbols. Any comment lines are allowed and must begin with an exclamation !  
! mark (!) in column one. Comments may appear to the right of a parameter !  
! specification to improve documentation. Comments will be ignored during !  
! reading. Blank lines are also allowed and ignored. Continuation lines in !  
! a parameter specification are allowed and must be preceded by a backslash !  
! (\). In some instances, more than one value is required for a parameter. !  
! If fewer values are provided, the last value is assigned for the entire !  
! parameter array. The multiplication symbol (*), without blank spaces in !  
! between, is allowed for a parameter specification. For example, in a two !  
! grids nested application: !  
!  
! AKT_BAK == 2*1.0d-6 2*5.0d-6 ! m2/s !  
!  
! indicates that the first two entries of array AKT_BAK, in fortran column- !  
! major order, will have the same value of "1.0d-6" for grid 1, whereas the !  
! next two entries will have the same value of "5.0d-6" for grid 2. !  
!  
! In multiple levels of nesting and/or multiple connected domains step-ups, !  
! "Ngrids" entries are expected for some of these parameters. In such case, !  
! the order of the entries for a parameter is extremely important. It must !
```

c4dvar.in Important Parameters

```
Nmethod == 0 ! normalization method (0: exact, 1:randomization)
Nrandom == 5000 ! randomization iterations
. . .
LdefNRM == T T T T ! Create a new normalization files
LwrtNRM == T T T T ! Compute and write normalization
. . .
CnormI(isFsur) = T ! 2D variable at RHO-points
CnormI(isUbar) = T ! 2D variable at U-points
CnormI(isVbar) = T ! 2D variable at V-points
CnormI(isUvel) = T ! 3D variable at U-points
CnormI(isVvel) = T ! 3D variable at V-points
CnormI(isTvar) = T T ! NT tracers
. . .
CnormB(isFsur) = T ! 2D variable at RHO-points
CnormB(isUbar) = T ! 2D variable at U-points
CnormB(isVbar) = T ! 2D variable at V-points
CnormB(isUvel) = T ! 3D variable at U-points
CnormB(isVvel) = T ! 3D variable at V-points
CnormB(isTvar) = T T ! NT tracers
. . .
CnormF(isUstr) = T ! surface U-momentum stress
CnormF(isVstr) = T ! surface V-momentum stress
CnormF(isTsur) = T T ! NT surface tracers flux
. . .
NRMnameM == wc13_nrm_m.nc ! model error (weak constraint)
NRMnameI == wc13_nrm_i.nc ! initial conditions
NRMnameB == wc13_nrm_b.nc ! open boundary conditions
NRMnameF == wc13_nrm_f.nc ! surface forcing (wind stress and net heat flux)
```


Normalization Method

- The **exact method** is very expensive on large grids.
- The normalization coefficients are computed by perturbing each model grid cell with a delta function scaled by the area (2D state variables) or volume (3D state variables), and then convolving with the squared-root adjoint and tangent linear diffusion operators.
- The **randomization method** is cheaper (Fisher and Courtier, 1985).
- The normalization coefficients are initialized with random numbers having a uniform distribution (drawn from a normal distribution with zero mean and unit variance). Then, they are scaled by the inverse squared-root of the cell area (2D state variables) or volume (3D state variables) and convolved with the squared-root adjoint and tangent linear diffusion operator over a specified number of iterations, **Nrandom**.
- The normalization coefficients need to be computed only once for a particular application provided that the grid, land/sea masking (if any), and decorrelation scales remain the same.

4D-Var Parameters: Decorrelation Scales

Horizontal and vertical stability and accuracy factors (< 1):

!		IC	Model	OBC	Sur For	
	Hgamma =	0.5	0.5	0.5	0.5	! horizontal operator
	Vgamma =	0.0005	0.0005	0.0005	0.0005	! vertical operator

Model Error correlations (m):

HdecayM(isFsur)	==	50.0d+3			! free-surface
HdecayM(isUbar)	==	50.0d+3			! 2D U-momentum
HdecayM(isVbar)	==	50.0d+3			! 2D V-momentum
HdecayM(isUvel)	==	50.0d+3			! 3D U-momentum
HdecayM(isVvel)	==	50.0d+3			! 3D V-momentum
HdecayM(isTvar)	==	50.0d+3	50.0d+3		! 1:NT tracers
VdecayM(isUvel)	==	30.0d0			! 3D U-momentum
VdecayM(isVvel)	==	30.0d0			! 3D V-momentum
VdecayM(isTvar)	==	30.0d0	30.0d0		! 1:NT tracers

4D-Var Parameters: Decorrelation Scales

Initial conditions correlations (m):

```
HdecayI(isFsur) == 50.0d+3           ! free-surface
HdecayI(isUbar) == 50.0d+3           ! 2D U-momentum
HdecayI(isVbar) == 50.0d+3           ! 2D V-momentum
HdecayI(isUvel) == 50.0d+3           ! 3D U-momentum
HdecayI(isVvel) == 50.0d+3           ! 3D V-momentum
HdecayI(isTvar) == 50.0d+3  50.0d+3  ! 1:NT tracers

VdecayI(isUvel) == 30.0d0            ! 3D U-momentum
VdecayI(isVvel) == 30.0d0            ! 3D V-momentum
VdecayI(isTvar) == 30.0d0  30.0d0    ! 1:NT tracers
```

Surface forcing correlations (m):

```
HdecayF(isUstr) == 100.0d+3          ! surface U-momentum stress
HdecayF(isVstr) == 100.0d+3          ! surface V-momentum stress
HdecayF(isTsur) == 100.0d+3  100.0d+3 ! 1:NT surface tracer flux
```

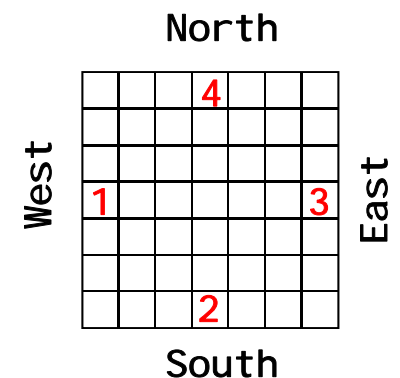
4D-Var Parameters: Decorrelation Scales

Open boundary conditions correlations (m):

!		1: west	2: south	3: east	4: north	
HdecayB(i sFsur)	==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! free-surface
HdecayB(i sUbar)	==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 2D U-momentum
HdecayB(i sVbar)	==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 2D V-momentum
HdecayB(i sUvel)	==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 3D U-momentum
HdecayB(i sVvel)	==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 3D V-momentum
HdecayB(i sTvar)	==	4*100.0d+3	4*100.0d+3			! 1:NT tracers
VdecayB(i sUvel)	==	30.0d0	30.0d0	30.0d0	30.0d0	! 3D U-momentum
VdecayB(i sVvel)	==	30.0d0	30.0d0	30.0d0	30.0d0	! 3D V-momentum
VdecayB(i sTvar)	==	4*30.d0	4*30.d0			! 1:NT tracers

Boundary edges to adjust (logical switches):

!		1	2	3	4	
Lobc(i sFsur)	==	T	T	F	T	! free-surface
Lobc(i sUbar)	==	T	T	F	T	! 2D U-momentum
Lobc(i sVbar)	==	T	T	F	T	! 2D V-momentum
Lobc(i sUvel)	==	T	T	F	T	! 3D U-momentum
Lobc(i sVvel)	==	T	T	F	T	! 3D V-momentum
Lobc(i sTvar)	==	T	T	F	T	\
		T	T	F	T	



Normalization Parameters File: c4dvar.in

```
! 4DVar assimilation input parameters.
!
!svn $Id: s4dvar.in 1256 2010-06-12 21:59:26Z arango $
!===== Hernan G. Arango ====
! Copyright (c) 2002-2010 The ROMS/TOMS Group
! Licensed under a MIT/X style license
! See License_ROMS.txt
!=====
!
! Input parameters can be entered in ANY order, provided that the parameter
! KEYWORD (usually, upper case) is typed correctly followed by "=" or "=="
! symbols. Any comment lines are allowed and must begin with an exclamation
! mark (!) in column one. Comments may appear to the right of a parameter
! specification to improve documentation. Comments will be ignored during
! reading. Blank lines are also allowed and ignored. Continuation lines in
! a parameter specification are allowed and must be preceded by a backslash
! (\). In some instances, more than one value is required for a parameter.
! If fewer values are provided, the last value is assigned for the entire
! parameter array. The multiplication symbol (*), without blank spaces in
! between, is allowed for a parameter specification. For example, in a two
! grids nested application:
!
!     AKT_BAK == 2*1.0d-6  2*5.0d-6                ! m2/s
!
! indicates that the first two entries of array AKT_BAK, in fortran column-
! major order, will have the same value of "1.0d-6" for grid 1, whereas the
! next two entries will have the same value of "5.0d-6" for grid 2.
!
! In multiple levels of nesting and/or multiple connected domains step-ups,
! "Ngrids" entries are expected for some of these parameters. In such case,
! the order of the entries for a parameter is extremely important. It must
! follow the same order (1:Ngrids) as in the state variable declaration. The
```

Job Script: job_normalization.sh

1. Set path definition to one directory up in the tree.

```
set Dir = `dirname ${PWD}`
```

2. Set string manipulations perl script.

```
set SUBSTITUTE = ${ROMS_ROOT}/ROMS/Bin/substitute
```

3. Copy nonlinear model initial conditions file.

```
cp -p ${Dir}/Data/wc13_ini.nc wc13_ini.nc
```

4. Set model error, initial conditions, boundary conditions and surface forcing error covariance standard deviations files.

```
set STDnameM = ../Data/wc13_std_m.nc  
set STDnameI = ../Data/wc13_std_i.nc  
set STDnameB = ../Data/wc13_std_b.nc  
set STDnameF = ../Data/wc13_std_f.nc
```

5. Set model error, initial conditions, boundary conditions and surface forcing error covariance normalization factors files.

```
set NRMnameM = ../Data/wc13_nrm_m.nc  
set NRMnameI = ../Data/wc13_nrm_i.nc  
set NRMnameB = ../Data/wc13_nrm_b.nc  
set NRMnameF = ../Data/wc13_nrm_f.nc
```

6. Modify 4D-Var template input script and specify above files.

```
set NORM = c4dvar.in  
if (-e $NORM) then  
  /bin/rm $NORM  
endif  
cp s4dvar.in $NORM
```

```
$SUBSTITUTE $NORM ocean_std_i.nc $STDnameI  
$SUBSTITUTE $NORM ocean_std_b.nc $STDnameB  
$SUBSTITUTE $NORM ocean_std_f.nc $STDnameF  
$SUBSTITUTE $NORM ocean_nrm_i.nc $NRMnameI  
$SUBSTITUTE $NORM ocean_nrm_b.nc $NRMnameB  
$SUBSTITUTE $NORM ocean_nrm_f.nc $NRMnameF  
$SUBSTITUTE $NORM ocean_obs.nc $OBSname  
$SUBSTITUTE $NORM ocean_hss.nc wc13_hss.nc  
$SUBSTITUTE $NORM ocean_lcz.nc wc13_lcz.nc  
$SUBSTITUTE $NORM ocean_mod.nc wc13_mod.nc  
$SUBSTITUTE $NORM ocean_err.nc wc13_err.nc
```

Job Script File: `job_normalization.sh`

```
#!/bin/csh -f
#
# svn $Id: job_normalization.sh 474 2010-06-25 20:19:44Z arango $
#####
# Copyright (c) 2002-2010 The ROMS/TOMS Group                                     #
# Licensed under a MIT/X style license                                           #
# See License_ROMS.txt                                                            #
#####
#
# 4D-Var error covariance normalization coefficients job script:                 #
#
# This script NEEDS to be run before any run:                                   #
#
# (1) It copies a new clean nonlinear model initial conditions                   #
# file. The nonlinear model is initialized from the                             #
# background or reference state.                                               #
# (2) Specify model, initial conditions, boundary conditions, and               #
# surface forcing error covariance input standard deviations                   #
# files.                                                                        #
# (3) Specify model, initial conditions, boundary conditions, and               #
# surface forcing error covariance input/output normalization                   #
# factors filenames.                                                            #
# (4) Create 4D-Var input script "c4dvar.in" from a template and               #
# specify the error covariance standard deviation, and error                   #
# covariance normalization factors files to be used.                           #
#
#####
# Set path definition to one directory up in the tree.
#
set Dir=`dirname ${PWD}``
```

Compile: build.sh

1. Set a local environmental variable to define the path to the directories where all this project's files are kept.

```
setenv MY_ROOT_DIR /home/arango/ocean/toms/repository
setenv MY_PROJECT_DIR ${PWD}
```

2. Location of your ROMS source code.

```
setenv MY_ROMS_SRC ${MY_ROOT_DIR}/branches/arango
```

3. Build script invoked CPP options.

```
setenv MY_CPP_FLAGS "-DNORMALIZATION"
```

4. Compiler selection environment variables.

```
setenv USE_MPI on
setenv USE_MPI_F90 on
setenv FORT pgi
```

5. Use custom library paths.

```
#setenv USE_MY_LIBS on
```

Libraries for PGI

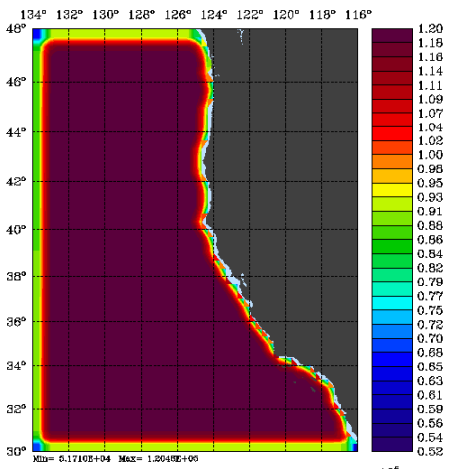
```
if ($?USE_MY_LIBS) then
  switch ($FORT)
  case "pgi"
    setenv ARPACK_LIBDIR /opt/pgi/soft/serial/ARPACK
    if ($?USE_MPI) then
      setenv PARPACK_LIBDIR /opt/pgi/soft/mpi ch/PARPACK
    endif

    if ($?USE_NETCDF4) then
      if ($?USE_MPI) then
        setenv NETCDF_INC_DIR /opt/pgi/soft/mpi ch/netcdf4/include
        setenv NETCDF_LIBDIR /opt/pgi/soft/mpi ch/netcdf4/lib
        setenv HDF5_LIBDIR /opt/pgi/soft/mpi ch/hdf5/lib
      else
        setenv NETCDF_INC_DIR /opt/pgi/soft/serial/netcdf4/include
        setenv NETCDF_LIBDIR /opt/pgi/soft/serial/netcdf4/lib
        setenv HDF5_LIBDIR /opt/pgi/soft/serial/hdf5/lib
      endif
    else
      setenv NETCDF_INC_DIR /opt/pgi/soft/serial/netcdf3/include
      setenv NETCDF_LIBDIR /opt/pgi/soft/serial/netcdf3/lib
    endif
  breaksw
endif
```

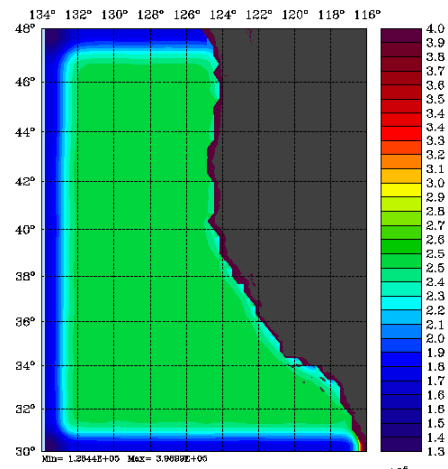

Build Script: **build.sh**

```
#!/bin/csh -f
#
# svn $Id: build.sh 474 2010-06-25 20:19:44Z arango $
# :::::::::::::::::::::::::::::::::::::::::::::::::::::::::::: John Wilkin :::
# Copyright (c) 2002-2010 The ROMS/TOMS Group ::::
# Licensed under a MIT/X style license ::::
# See License_ROMS.txt ::::
# :::::::::::::::::::::::::::::::::::::::::::::::::::::::::::: Hernan G. Arango :::
# ::::
# ROMS/TOMS Compiling Script ::::
# ::::
# Script to compile an user application where the application-specific ::::
# files are kept separate from the ROMS source code. ::::
# ::::
# Q: How/why does this script work? ::::
# ::::
# A: The ROMS makefile configures user-defined options with a set of ::::
# flags such as ROMS_APPLICATION. Browse the makefile to see these. ::::
# If an option in the makefile uses the syntax ?= in setting the ::::
# default, this means that make will check whether an environment ::::
# variable by that name is set in the shell that calls make. If so ::::
# the environment variable value overrides the default (and the ::::
# user need not maintain separate makefiles, or frequently edit ::::
# the makefile, to run separate applications). ::::
# ::::
# Usage: ::::
# ::::
# ./build.sh [options] ::::
# ::::
# Options: ::::
# ::::
# -j [N] Compile in parallel using N CPUs ::::
```

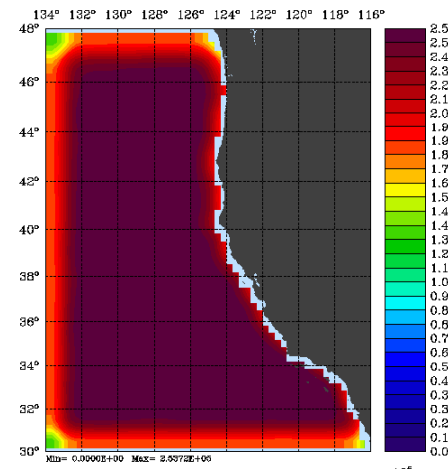
Error Covariance Normalization Coefficients



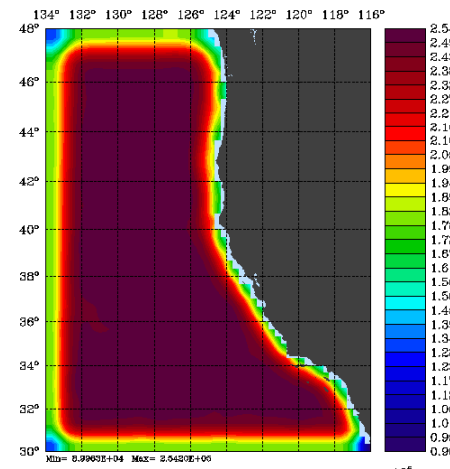
Free-surface



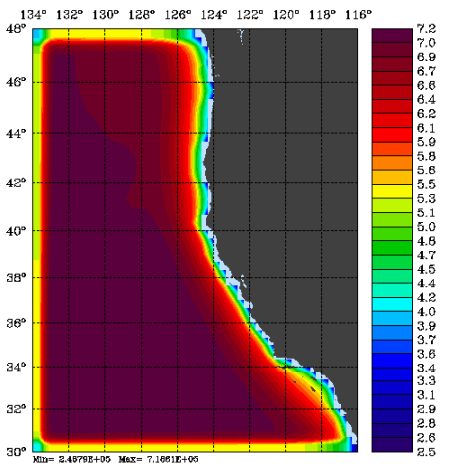
T_x



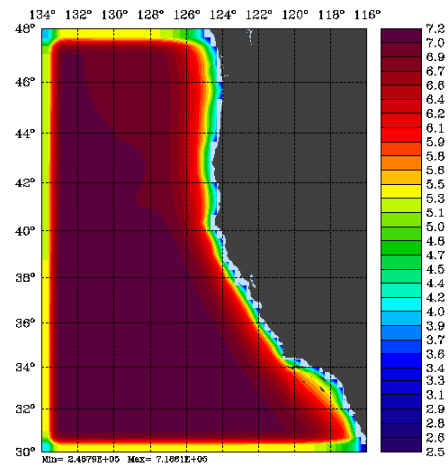
T_y



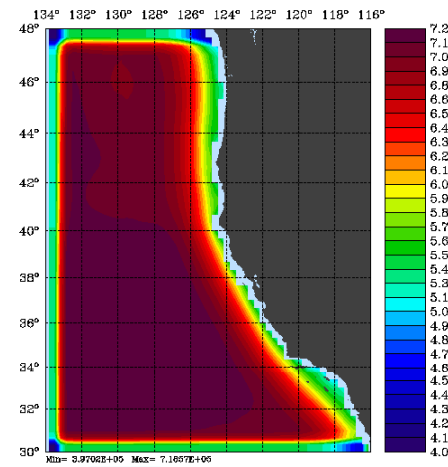
Net Heat Flux



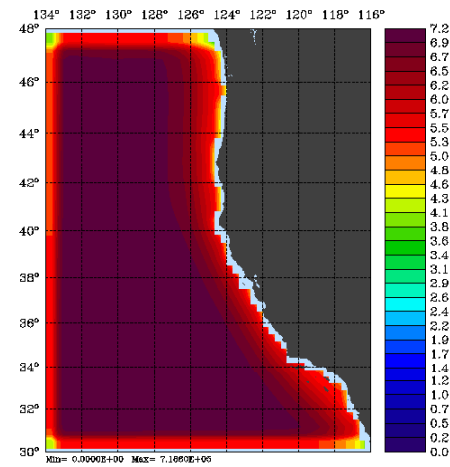
Temperature



Salinity



3D U-Momentum



3D V-Momentum

References

- Fisher, M. and P. Courtier, 1995: Estimating the covariance matrices of analysis and forecast error in variational data assimilation. ECMWF Tech. Memo, **220**.
- Weaver, A.T. and P. Courtier, 2001: Correlation modelling on the sphere using a generalized diffusion equation. *Q. J. R. Meteorol. Soc.*, **127**, 1815-1846.