EXERCISE 5: Array Modes

Introduction

As described in Lecture 4, the 4D-Var state-vector increments $\delta \mathbf{x}_{\mathbf{a}}(t)$ can be expressed as a weighted sum of the array modes:

$$\delta \mathbf{x}_{\mathbf{a}}(t) = \sum_{i=1}^{M} \lambda_i^{-1} \left(\hat{\mathbf{w}}_i^{\mathrm{T}} \mathbf{R}^{-1/2} \mathbf{d} \right) \boldsymbol{\Psi}_i(t)$$

where $(\lambda_i, \hat{\mathbf{w}}_i)$ are the eigenpairs of the preconditioned stabilized representer matrix $(\mathbf{R}^{-1/2}\mathbf{G}\mathbf{D}\mathbf{G}^{\mathsf{T}}\mathbf{R}^{-1/2} + \mathbf{I})$. The array modes corresponding the largest eigenvalue represent the interpolation patterns for the observations that are most stable with respect to changes in the innovation vector \mathbf{d} , since the array modes depend *only* on the observation locations and not on the observation values.

Running the array mode driver

To compute the array modes, you must first run R4D-Var or 4D-PSAS because the array mode driver will use the Lanczos vectors generated by your dual 4D-Var calculation.

To run this exercise, go first to the directory WC13/ARRAY_MODES, and follow the directions in the **Readme** file. The only change that you need to make is to s4dvar.in, where you will select the array mode that you wish to calculate (you may only calculate one mode at a time). The choice of array mode is determined by the parameter *Nvct*. The array modes are referenced in reverse order, so choosing *Nvct=Ninner* corresponds to the array mode with the largest eigenvalue, *Nvct=Ninner-1* is the array mode with second largest eigenvalue, and so on. Note that *Nvct* must be assigned a numeric value (i.e. *Nvct=50* for the 4D-Var case you ran in Exercise 3).

NOTE: Before running the array mode driver, you will need to ensure that you copy the file **EX3/wc13_mod.nc** generated during Exercise 3 into **WC13/R4DVAR** or **WC13/PSAS** as appropriate.

Plotting your results

Use WC13/plotting/plot_array_modes.m to plot a selection of fields for you chosen array mode.