

Tutorial 9:

Computing Normalization

Coefficients for Covariance

Models

Prior Error Covariance Modeling

Recall: $B_x = K_b \Sigma C \Sigma^T K_b^T$

C is a correlation matrix for the unbalanced increments, and is modeled as the solution of a diffusion equation:

$$\partial \mathbf{x} / \partial t - \kappa \nabla^2 \mathbf{x} = 0 \quad \rightarrow \quad C' \mathbf{x}$$

But, C' is arbitrary at this stage, and must be normalized to ensure that the range is ± 1 as required for a correlation function. Therefore we define:

$$C = \Lambda C' \Lambda^T$$

where Λ is a diagonal matrix with elements $(c'_{ii})^{-1/2}$

Finally: $B_x = K_b \Sigma \Lambda C' \Lambda^T \Sigma^T K_b^T$

Computing Λ

(define NORMALIZATION)

Following Weaver & Courtier (2001) we employ two methods for computing the elements of Λ :

(i) Exact method (Nmethod=0):

$C'e_i \rightarrow i^{th}$ column of C' ; save c_{ii}

where $e_i^T = (0, 0, \dots, 0, \underset{i^{th} \text{ element}}{\overset{\uparrow}{1}}, 0, \dots, 0)$

Requires N_{grid} runs of diffusion operators:
impractical for v. large grids.

Computing Λ

(ii) Randomization method (Nmethod=1):

Estimate the diagonal elements c'_{ii} of C' from:

$$C' \approx \frac{1}{M} \sum_{i=1}^M \xi C' \xi^T = \tilde{C}$$

where ξ is a random vector: $\xi \rightarrow N(\mathbf{0}, \mathbf{I})$

M is the sample size. As $M \rightarrow \infty$, $\tilde{C} \rightarrow C'$
(Nrandom)

Uncertainty in elements of Λ^{-1} : $(2M)^{-1/2}$

Practical requirement: $M \ll N_{grid}$

(Fisher and Courtier, 1995)

Computing Λ

Practicalities:

- choose M and run normalization driver
- choose another seed and run again
- compare the estimates – are they similar
- compute means of the two M samples
- repeat as necessary until mean does not change significantly

Normalization Tutorial Wiki Page

The screenshot shows a web browser window titled "4DVar Normalization Tutorial - WikiROMS". The URL is https://www.myroms.org/index.php/Error_Covariance_Normalization. The page content is as follows:

Error Covariance Normalization

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Introduction [edit]

In this tutorial you will compute the 4D-Var error covariance (**D**) normalization factors for the California Current System application [WC13](#).

The error covariance matrix, $D = \text{diag}(B_x, B_b, B_f, Q)$, is very large and not well known. **B** and **Q** are modeled as the solution of a diffusion equation following [Weaver and Courtier \(2001\)](#) methodology. Each covariance matrix is factorized as $B = K \Sigma C \Sigma^T K^T$, where **C** is a univariate correlation matrix, **Σ** is a diagonal matrix of error standard deviations, and **K** is a multivariate balance operator. The normalization coefficients are needed to ensure that the diagonal elements of the associated correlation matrix **C** are equal to unity.

There are two methods to compute the error covariance normalization coefficients: **exact** and **randomization** (an approximation).

The **exact method** is very expensive on large grids. The normalization coefficients are computed by perturbing each model grid cell with a delta function scaled by the area (2D state variables) or volume (3D state variables), and then by convolving with the squared-root adjoint and tangent linear diffusion operators.

In the cheaper approximate method, the normalization coefficients are computed using the **randomization approach** of [Fisher and Courtier \(1995\)](#). The coefficients are initialized with random numbers having a uniform distribution (drawn from a normal distribution with zero mean and unit variance). Then, they are scaled by the inverse squared-root of the cell area (2D state variable) or volume (3D state variable) and convolved with the squared-root adjoint and tangent diffusion operators over a specified number of iterations, **Nrandom**.

Since the grid for [WC13](#) is relatively small, the error covariance normalization coefficients are computed using the **exact** method. They need to be computed only once for a particular application provided that the grid, land/sea masking (if any), and decorrelation scales remain the same.

Model Set-up [edit]

The [WC13](#) model domain is shown in Fig. 1 and has open boundaries along the northern, western, and southern edges of the model domain.

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WC13 C-preprocessing Options

(Basic Configuration)

Momentum Equations Options:

```
#define UV_ADV           including advection terms
#define UV_COR           including Coriolis term
#define UV_U3HADVECTION 3rd-order Upstream Horizontal advection
#define UV_C4VADVECTION 4th-order Centered Vertical advection
#define DJ_GRADPS         splines density Jacobian PGF
#define UV_QDRAG          quadratic bottom friction
#define UV_VIS2           harmonic horizontal mixing
#define MIX_S_UV          mixing along s-levels
#define SPLINES_VVISC     parabolic Splines for vertical viscosity
```

Tracers Equations Options:

```
#define TS_U3HADVECTION 3rd-order Upstream horizontal advection
#define TS_C4VADVECTION 4th-order Centered advection
#define TS_DIF2           harmonic horizontal mixing
#define MIX_GEO_TS        mixing along geo-potentials
#define SALINITY          including salinity
#define NONLIN_EOS        nonlinear equation of state
#define SPLINES_VDIFF     parabolic splines for vertical Diffusion

#define ANA_BTFLUX        analytical bottom Temp flux
#define ANA_BSFLUX        analytical bottom Salt flux
```

Surface Forcing Options:

```
#define BULK_FLUXES     surface bulk fluxes parameterization

#define DIURNAL_SRFLUX   modulate shortwave by the local diurnal cycle
#define EMINUSP           compute Salt Flux using E-P
#define LONGWAVE_OUT      compute outgoing longwave radiation
#define SOLAR_SOURCE      solar radiation source term
```

Vertical Turbulent Mixing Parameterization Options:

```
#define GLS_MIXING      Generic Length Scale Mixing (K-omega)
#ifndef GLS_MIXING
#define N2S2_HORAVG
#define KANTHA_CLAYSON
#define RI_SPLINES
#endif
```

Model Configuration Options:

```
#define SOLVE3D         solve 3D primitive equations
#define CURVGRID          curvilinear grid
#define MASKING           land/sea masking
#define SPHERICAL         spherical grid
#define PROFILE           time profiling

#define ANA_SPONGE        analytical viscosity/diffusion sponge
```

WC13 C-preprocessing Options

(Error Covariance Configuration)

Algorithm:

```
#define NORMALIZATION      primal form of incremental strong constraint 4D-Var  
#define ANA_INITAL         analytical initial conditions (zero fields)
```

Control Vector:

```
#define ADJUST_BOUNDARY    open boundary conditions increments  
#define ADJUST_STFLUX       surface tracer flux increments  
#define ADJUST_WSTRESS      surface wind stress increments
```

Error Covariance Modeling:

```
#define CORRELATION        model error covariance correlation with diffusion operators  
#define FULL_GRID           consider both interior and boundary points  
#define VCONVOLUTION        Vertical correlation modeling  
#define IMPLICIT_VCON       Implicit vertical diffusion operator  
#undef BALANCE_OPERATOR    Multivariate balance constraint  
#ifdef BALANCE_OPERATOR   # define ZETA_ELLIPTIC      SSH elliptic equation method  
#endif
```

Prior:

```
#define FORWARD_READ        read basic state linearization in TLM and ADM files  
#define FORWARD_WRITE       writing basic state by the NLM  
#define FORWARD_MIXING      processing basic state vertical mixing coefficients  
#define NL_BULK_FLUXES      surface kinematic fluxes from nonlinear model
```

I/O :

```
#define OUT_DOUBLE          double precision data in output NLM, TLM, and ADM
```

Include File: wc13.h

```
/*
** svn $Id: wc13.h 1024 2020-05-14 03:36:12Z arango $
*****
** Copyright (c) 2002-2020 The ROMS/TOMS Group
** Licensed under a MIT/X style license
** See License_ROMS.txt
*****
**

** Options for the California Current System, 1/3 degree resolution.

**

** Application flag: WC13
** Input script: roms_wc13.in
** s4dvar.in
**

** Available Drivers options: choose only one and activate it in the
** build.sh script (MY_CPP_FLAGS definition)
**

** AD_SENSITIVITY          Adjoint Sensitivity Driver
** AFT_EIGENMODES           Adjoint Finite Time Eigenmodes
** ARRAY_MODES               Stabilized representer matrix array modes
** CLIPPING                  Stabilized representer matrix clipped analysis
** CORRELATION                Background-error Correlation Check
** GRADIENT_CHECK             TLM/ADM Gradient Check
** FORCING_SV                  Forcing Singular Vectors
** FT_EIGENMODES               Finite Time Eigenmodes
** I4DVAR                     Incremental, strong constraint I4D-Var
** NLM_DRIVER                  Nonlinear Basic State trajectory
** OPT_PERTURBATION            Optimal perturbations
** PICARD_TEST                 Picard Iterations Test
** PDI_ADVAR
```

4D-Var Error Covariance Normalization Files

- Four different error covariance normalization coefficients NetCDF files are required in ROMS 4D-Var algorithms to ensure that the diagonal elements of the associated correlation matrix (**C**) are equal to unity:
 - Model error normalization file, if weak constraint
 - Initial conditions normalization file
 - Open boundary conditions normalization file, if **ADJUST_BOUNDARY**
 - Surface forcing normalization file, if **ADJUST_WSTRESS** and/or **ADJUST_STFLUX**
- These normalization NetCDF files are specified in 4D-Var input script as:

```
NRMnameM == ../Data/wc13_nrm_m.nc  
NRMnameI == ../Data/wc13_nrm_i.nc  
NRMnameB == ../Data/wc13_nrm_b.nc  
NRMnameF == ../Data/wc13_nrm_f.nc
```

Model Error and Initial Conditions Metadata

Variables:

```
double zeta(ocean_time, eta_rho, xi_rho) ;
    zeta:long_name = "free-surface, initial conditions error covariance normalization" ;
    zeta:units = "meter" ;
    zeta:time = "ocean_time" ;
    zeta:coordinates = "lon_rho lat_rho ocean_time" ;
double ubar(ocean_time, eta_u, xi_u) ;
    ubar:long_name = "vertically integrated u-momentum component, initial conditions error covariance normalization" ;
    ubar:units = "meter" ;
    ubar:time = "ocean_time" ;
    ubar:coordinates = "lon_u lat_u ocean_time" ;
double vbar(ocean_time, eta_v, xi_v) ;
    vbar:long_name = "vertically integrated v-momentum component, initial conditions error covariance normalization" ;
    vbar:units = "meter" ;
    vbar:time = "ocean_time" ;
    vbar:coordinates = "lon_v lat_v ocean_time" ;
double u(ocean_time, s_rho, eta_u, xi_u) ;
    u:long_name = "u-momentum component, initial conditions error covariance normalization" ;
    u:units = "meter" ;
    u:time = "ocean_time" ;
    u:coordinates = "lon_u lat_u s_rho ocean_time" ;
double v(ocean_time, s_rho, eta_v, xi_v) ;
    v:long_name = "v-momentum component, initial conditions error covariance normalization" ;
    v:units = "meter" ;
    v:time = "ocean_time" ;
    v:coordinates = "lon_v lat_v s_rho ocean_time" ;
double temp(ocean_time, s_rho, eta_rho, xi_rho) ;
    temp:long_name = "potential temperature, initial conditions error covariance normalization" ;
    temp:units = "meter" ;
    temp:time = "ocean_time" ;
    temp:coordinates = "lon_rho lat_rho s_rho ocean_time" ;
double salt(ocean_time, s_rho, eta_rho, xi_rho) ;
    salt:long_name = "salinity, initial conditions error covariance normalization" ;
    salt:units = "meter" ;
    salt:time = "ocean_time" ;
    salt:coordinates = "lon_rho lat_rho s_rho ocean_time" ;
```

Open Boundary Conditions Metadata

dimensions:

```
xi_rho = 56 ;
eta_rho = 55 ;

. . .
IorJ = 56 ;
boundary = 4 ;
```

variables:

```
. . .

double zeta.obc(ocean_time, boundary, IorJ) ;
zeta.obc:long_name = "free-surface, open boundaries conditions error covariance normalization" ;
zeta.obc:units = "meter" ;
zeta.obc:time = "ocean_time" ;
double ubar.obc(ocean_time, boundary, IorJ) ;
ubar.obc:long_name = "vertically integrated u-momentum component, open boundaries conditions error covariance normalization" ;
ubar.obc:units = "meter second-1" ;
ubar.obc:time = "ocean_time" ;
double vbar.obc(ocean_time, boundary, IorJ) ;
vbar.obc:long_name = "vertically integrated v-momentum component, open boundaries conditions error covariance normalization" ;
vbar.obc:units = "meter second-1" ;
vbar.obc:time = "ocean_time" ;
double u.obc(ocean_time, s_rho, boundary, IorJ) ;
u.obc:long_name = "u-momentum component, open boundaries conditions error covariance normalization" ;
u.obc:units = "meter second-1" ;
u.obc:time = "ocean_time" ;
double v.obc(ocean_time, s_rho, boundary, IorJ) ;
v.obc:long_name = "v-momentum component, open boundaries conditions error covariance normalization" ;
v.obc:units = "meter second-1" ;
v.obc:time = "ocean_time" ;
double temp.obc(ocean_time, s_rho, boundary, IorJ) ;
temp.obc:long_name = "potential temperature, open boundaries conditions error covariance normalization" ;
temp.obc:units = "Celsius" ;
temp.obc:time = "ocean_time" ;
double salt.obc(ocean_time, s_rho, boundary, IorJ) ;
salt.obc:long_name = "salinity, open boundaries conditions error covariance normalization" ;
salt.obc:time = "ocean_time" ;

// global attributes:
. . .
:boundary_index = "West=1, South=2, East=3, North=4"
```

Surface Forcing Metadata

dimensions:

```
xi_rho = 56 ;
xi_u = 55 ;
xi_v = 56 ;
eta_rho = 55 ;
eta_u = 55 ;
eta_v = 54 ;
s_rho = 30 ;
ocean_time = UNLIMITED ; // (1 currently)
```

variables:

```
double sustr(ocean_time, eta_u, xi_u) ;
sustr:long_name = "surface u-momentum stress, error covariance normalization" ;
sustr:units = "newton meter-2" ;
sustr:time = "ocean_time" ;
sustr:coordinates = "lon_u lat_u ocean_time" ;
double svstr(ocean_time, eta_v, xi_v) ;
svstr:long_name = "surface v-momentum stress, error covariance normalization" ;
svstr:units = "newton meter-2" ;
svstr:time = "ocean_time" ;
svstr:coordinates = "lon_v lat_v ocean_time" ;
double shflux(ocean_time, eta_rho, xi_rho) ;
shflux:long_name = "surface net heat flux, error covariance normalization" ;
shflux:units = "watt meter-2" ;
shflux:negative = "upward flux, cooling" ;
shflux:positive = "downward flux, heating" ;
shflux:time = "ocean_time" ;
shflux:coordinates = "lon_rho lat_rho ocean_time" ;
double ssflux(ocean_time, eta_rho, xi_rho) ;
ssflux:long_name = "surface net salt flux (E-P)*SALT, error covariance normalization" ;
ssflux:units = "meter second-1" ;
ssflux:time = "ocean_time" ;
ssflux:coordinates = "lon_rho lat_rho ocean_time" ;

// global attributes:
:type = "ROMS 4D-Var surface forcing error covariance normalization" ;
:title = "California Current System, 1/3 degree resolution (WC13)" ;
:Conventions = "CF-1.4" ;
:grd_file = "test/wc13/Data/wc13_grd.nc" ;
```

Standard Input File: roms_wc13.in

```
!
! ROMS/TOMS Standard Input parameters.
!

!svn $Id: roms_wc13.in 971 2019-07-09 03:02:57Z arango $
!===== Hernan G. Arango ===
! Copyright (c) 2002-2019 The ROMS/TOMS Group !
! Licensed under a MIT/X style license !
! See License_ROMS.txt !
!=

!

! Input parameters can be entered in ANY order, provided that the parameter !
! KEYWORD (usually, upper case) is typed correctly followed by "=" or "==" !
! symbols. Any comment lines are allowed and must begin with an exclamation !
! mark (!) in column one. Comments may appear to the right of a parameter !
! specification to improve documentation. Comments are ignored during !
! reading. Blank lines are also allowed and ignored. Continuation lines in !
! a parameter specification are allowed if preceded by a backslash (\). In !
! some instances, more than one value is required for a parameter. If fewer !
! values are provided, the last value is assigned for the entire parameter !
! array. The multiplication symbol (*), without blank spaces in between,
! is allowed for a parameter specification. For example, in two grids nested !
! application:
!

! AKT_BAK == 2*1.0d-6 2*5.0d-6           ! m2/s !
!

! indicates that the first two entries of array AKT_BAK, in fortran column-
! major order, will have the same value of "1.0d-6" for grid 1, whereas the !
! next two entries will have the same value of "5.0d-6" for grid 2.
!
```

C4dvar.in Important Parameters

```
Nmethod == 0          ! normalization method: 0=Exact (expensive) or 1=Approximated (randomization)
Nrrandom == 5000      ! randomization iterations
.
.
LdefNRM == F F F F   ! Create a new normalization files (model, IC, OBC, surface forcing)
LwrtNRM == F F F F   ! Compute and write normalization (model, IC, OBC, surface forcing)
.
.
CnormM(isFsur) = T   ! model error covariance, 2D variable at RHO-points
CnormM(isUbar) = T   ! model error covariance, 2D variable at U-points
CnormM(isVbar) = T   ! model error covariance, 2D variable at V-points
CnormM(isUvel) = T   ! model error covariance, 3D variable at U-points
CnormM(isVvel) = T   ! model error covariance, 3D variable at V-points
CnormM(isTvar) = T T ! model error covariance, NT tracers
.
.
CnormI(isFsur) = T   ! IC error covariance, 2D variable at RHO-points
CnormI(isUbar) = T   ! IC error covariance, 2D variable at U-points
CnormI(isVbar) = T   ! IC error covariance, 2D variable at V-points
CnormI(isUvel) = T   ! IC error covariance, 3D variable at U-points
CnormI(isVvel) = T   ! IC error covariance, 3D variable at V-points
CnormI(isTvar) = T T ! IC error covariance, NT tracers
.
.
CnormB(isFsur) = T   ! OBC error covariance, 2D variable at RHO-points
CnormB(isUbar) = T   ! OBC error covariance, 2D variable at U-points
CnormB(isVbar) = T   ! OBC error covariance, 2D variable at V-points
CnormB(isUvel) = T   ! OBC error covariance, 3D variable at U-points
CnormB(isVvel) = T   ! OBC error covariance, 3D variable at V-points
CnormB(isTvar) = T T ! OBC error covariance, NT tracers
.
.
CnormF(isUstr) = T   ! surface forcing error covariance, U-momentum stress
CnormF(isVstr) = T   ! surface forcing error covariance, V-momentum stress
CnormF(isTsur) = T T ! Surface forcing error covariance, NT tracers fluxes
.
.
NRMnameM == wc13_nrm_m.nc ! model error (weak constraint)
NRMnameI == wc13_nrm_i.nc ! initial conditions
NRMnameB == wc13_nrm_b.nc ! open boundary conditions
NRMnameF == wc13_nrm_f.nc ! surface forcing (wind stress and net heat flux)
```

C4dvar.in 4D-Var Parameters: Decorrelation Scales

Horizontal and vertical stability and accuracy factors (< 1) :

!	IC	Model	OBC	Sur For	
	Hgamma = 0.5	0.5	0.5	0.5	! horizontal operator
	Vgamma = 0.0005	0.0005	0.0005	0.0005	! vertical operator

Model error correlations (m) :

HdecayM(isFsur) == 50.0d+3		! free-surface	(16 convolutions)
HdecayM(isUbar) == 50.0d+3		! 2D U-momentum	(16 convolutions)
HdecayM(isVbar) == 50.0d+3		! 2D V-momentum	(16 convolutions)
HdecayM(isUvel) == 50.0d+3		! 3D U-momentum	(16 convolutions)
HdecayM(isVvel) == 50.0d+3		! 3D V-momentum	(16 convolutions)
HdecayM(isTvar) == 50.0d+3	50.0d+3	! 1:NT tracers	(16 convolutions)
VdecayM(isUvel) == 30.0d0		! 3D U-momentum	(8 convolutions)
VdecayM(isVvel) == 30.0d0		! 3D V-momentum	(8 convolutions)
VdecayM(isTvar) == 30.0d0	30.0d0	! 1:NT tracers	(8 convolutions)

Initial conditions error correlations (m) :

HdecayI(isFsur) == 50.0d+3		! free-surface	(16 convolutions)
HdecayI(isUbar) == 50.0d+3		! 2D U-momentum	(16 convolutions)
HdecayI(isVbar) == 50.0d+3		! 2D V-momentum	(16 convolutions)
HdecayI(isUvel) == 50.0d+3		! 3D U-momentum	(16 convolutions)
HdecayI(isVvel) == 50.0d+3		! 3D V-momentum	(16 convolutions)
HdecayI(isTvar) == 50.0d+3	50.0d+3	! 1:NT tracers	(16 convolutions)
VdecayI(isUvel) == 30.0d0		! 3D U-momentum	(8 convolutions)
VdecayI(isVvel) == 30.0d0		! 3D V-momentum	(8 convolutions)
VdecayI(isTvar) == 30.0d0	30.0d0	! 1:NT tracers	(8 convolutions)

Surface forcing error correlations (m) :

HdecayF(isUstr) == 100.0d+3		! surface U-momentum stress	(66 convolutions)
HdecayF(isVstr) == 100.0d+3		! surface V-momentum stress	(66 convolutions)
HdecayF(isTsurr) == 100.0d+3	100.0d+3	! 1:NT surface tracer flux	(66 convolutions)

Normalization Method

- The **exact method** is very expensive on large grids.
- The normalization coefficients are computed by perturbing each model grid cell with a delta function scaled by the area (2D state variables) or volume (3D state variables), and then convolving with the squared-root adjoint and tangent linear diffusion operators. The diffusion operator is self-adjointed.
- The **randomization method** is cheaper (Fisher and Courtier, 1985).
- The normalization coefficients are initialized with random numbers having a uniform distribution (drawn from a normal distribution with zero mean and unit variance). Then, they are scaled by the inverse squared-root of the cell area (2D state variables) or volume (3D state variables) and convolved with the squared-root adjoint and tangent linear diffusion operator over a specified number of iterations, **Nrandom**.
- The normalization coefficients need to be computed only once for a particular application provided that the grid, land/sea masking (if any), and decorrelation scales remain the same.

4D-Var Parameters: Decorrelation Scales

Horizontal and vertical stability and accuracy factors (< 1) :

!	IC	Model	OBC	Sur For	
	Hgamma = 0.5	0.5	0.5	0.5	! horizontal operator
	Vgamma = 0.0005	0.0005	0.0005	0.0005	! vertical operator

Model Error correlations (m) :

HdecayM(isFsur) == 50.0d+3		! free-surface	(16 convolutions)
HdecayM(isUbar) == 50.0d+3		! 2D U-momentum	(16 convolutions)
HdecayM(isVbar) == 50.0d+3		! 2D V-momentum	(16 convolutions)
HdecayM(isUvel) == 50.0d+3		! 3D U-momentum	(16 convolutions)
HdecayM(isVvel) == 50.0d+3		! 3D V-momentum	(16 convolutions)
HdecayM(isTvar) == 50.0d+3	50.0d+3	! 1:NT tracers	(16 convolutions)
VdecayM(isUvel) == 30.0d0		! 3D U-momentum	(8 convolutions)
VdecayM(isVvel) == 30.0d0		! 3D V-momentum	(8 convolutions)
VdecayM(isTvar) == 30.0d0	30.0d0	! 1:NT tracers	(8 convolutions)

4D-Var Parameters: Decorrelation Scales

Initial conditions correlations (m) :

HdecayI(isFsur) == 50.0d+3	! free-surface	(16 convolutions)
HdecayI(isUbar) == 50.0d+3	! 2D U-momentum	(16 convolutions)
HdecayI(isVbar) == 50.0d+3	! 2D V-momentum	(16 convolutions)
HdecayI(isUvel) == 50.0d+3	! 3D U-momentum	(16 convolutions)
HdecayI(isVvel) == 50.0d+3	! 3D V-momentum	(16 convolutions)
HdecayI(isTvar) == 50.0d+3 50.0d+3	! 1:NT tracers	(16 convolutions)
VdecayI(isUvel) == 30.0d0	! 3D U-momentum	(8 convolutions)
VdecayI(isVvel) == 30.0d0	! 3D V-momentum	(8 convolutions)
VdecayI(isTvar) == 30.0d0 30.0d0	! 1:NT tracers	(8 convolutions)

Surface forcing correlations (m) :

HdecayF(isUstr) == 100.0d+3	! surface U-momentum stress	(66 convolutions)
HdecayF(isVstr) == 100.0d+3	! surface V-momentum stress	(66 convolutions)
HdecayF(isTsurr) == 100.0d+3 100.0d+3	! 1:NT surface tracer flux	(66 convolutions)

4D-Var Parameters: Decorrelation Scales

Open boundary conditions correlations (m) :

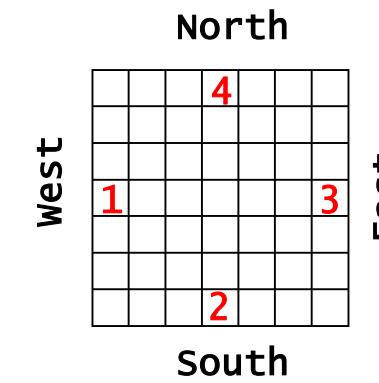
! 1: west 2: south 3: east 4: north

HdecayB(isFsur) ==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! free-surface
HdecayB(isubar) ==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 2D U-momentum
HdecayB(isvbar) ==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 2D V-momentum
HdecayB(isUvel) ==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 3D U-momentum
HdecayB(isVvel) ==	100.0d+3	100.0d+3	100.0d+3	100.0d+3	! 3D V-momentum
HdecayB(isTvar) ==	4*100.0d+3	4*100.0d+3			! 1:NT tracers
VdecayB(isUvel) ==	30.0d0	30.0d0	30.0d0	30.0d0	! 3D U-momentum
VdecayB(isVvel) ==	30.0d0	30.0d0	30.0d0	30.0d0	! 3D V-momentum
VdecayB(isTvar) ==	4*30.d0	4*30.d0			! 1:NT tracers

Boundary edges to adjust (logical switches) :

! 1 2 3 4

Lobc(isFsur) ==	T	T	F	T	! free-surface
Lobc(isubar) ==	T	T	F	T	! 2D U-momentum
Lobc(isvbar) ==	T	T	F	T	! 2D V-momentum
Lobc(isUvel) ==	T	T	F	T	! 3D U-momentum
Lobc(isVvel) ==	T	T	F	T	! 3D V-momentum
Lobc(isTvar) ==	T	T	F	T	\
	T	T	F	T	



Normalization Parameters File: c4dvar.in

```
! 4DVar assimilation input parameters.  
!  
!svn $Id: s4dvar.in 971 2019-07-09 03:02:57Z arango $  
!===== Hernan G. Arango ===  
! Copyright (c) 2002-2019 The ROMS/TOMS Group !  
! Licensed under a MIT/X style license !  
! See License_ROMS.txt !  
!=  
!  
! Input parameters can be entered in ANY order, provided that the parameter !  
! KEYWORD (usually, upper case) is typed correctly followed by "=" or "==" !  
! symbols. Any comment lines are allowed and must begin with an exclamation !  
! mark (!) in column one. Comments may appear to the right of a parameter !  
! specification to improve documentation. Comments will be ignored during !  
! reading. Blank lines are also allowed and ignored. Continuation lines in !  
! a parameter specification are allowed and must be preceded by a backslash !  
! (\). In some instances, more than one value is required for a parameter. !  
! If fewer values are provided, the last value is assigned for the entire !  
! parameter array. The multiplication symbol (*), without blank spaces in !  
! between, is allowed for a parameter specification. For example, in a two !  
! grids nested application:  
!  
! AKT_BAK == 2*1.0d-6 2*5.0d-6 ! m2/s  
!  
! indicates that the first two entries of array AKT_BAK, in fortran column- !  
! major order, will have the same value of "1.0d-6" for grid 1, whereas the !  
! next two entries will have the same value of "5.0d-6" for grid 2.  
!  
! In multiple levels of nesting and/or multiple connected domains step-ups,  
! "****" are inserted for some of the parameters. To ----- !
```

Job Script: job_normalization.csh

1. Set path definition to one directory up in the tree.

```
set Dir = `dirname ${PWD}`
```

2. Set string manipulations perl script.

```
set SUBSTITUTE =
${ROMS_ROOT}/ROMS/Bin/substitute
```

3. Set model error, initial conditions, boundary conditions and surface forcing error covariance standard deviations files.

```
set STDnameM = ./Data/wc13_std_m.nc
set STDnameI = ./Data/wc13_std_i.nc
set STDnameB = ./Data/wc13_std_b.nc
set STDnameF = ./Data/wc13_std_f.nc
```

4. Set model error, initial conditions, boundary conditions and surface forcing error covariance normalization factors files.

```
set NRMnameM = ./Data/wc13_nrm_m.nc
set NRMnameI = ./Data/wc13_nrm_i.nc
set NRMnameB = ./Data/wc13_nrm_b.nc
set NRMnameF = ./Data/wc13_nrm_f.nc
```

5. Modify 4D-Var template input script and specify above files.

```
set NORM = c4dvar.in
if (-e $NORM) then
    /bin/rm $NORM
endif
cp s4dvar.in $NORM

$SUBSTITUTE $NORM roms_std_m.nc $STDnameM
$SUBSTITUTE $NORM roms_std_i.nc $STDnameI
$SUBSTITUTE $NORM roms_std_b.nc $STDnameB
$SUBSTITUTE $NORM roms_std_f.nc $STDnameF
$SUBSTITUTE $NORM roms_nrm_m.nc $NRMnameM
$SUBSTITUTE $NORM roms_nrm_i.nc $NRMnameI
$SUBSTITUTE $NORM roms_nrm_b.nc $NRMnameB
$SUBSTITUTE $NORM roms_nrm_f.nc $NRMnameF
$SUBSTITUTE $NORM roms_obs.nc $OBSname
$SUBSTITUTE $NORM roms_hss.nc wc13_hss.nc
$SUBSTITUTE $NORM roms_lcz.nc wc13_lcz.nc
$SUBSTITUTE $NORM roms_mod.nc wc13_mod.nc
$SUBSTITUTE $NORM roms_err.nc wc13_err.nc
```

Job Script File: job_normalization.csh

```
#!/bin/csh -f
#
# svn $Id: job_normalization.csh 977 2019-07-26 06:01:07Z arango $
#####
# Copyright (c) 2002-2019 The ROMS/TOMS Group
# Licensed under a MIT/X style license
# See License_ROMS.txt
#####
#
# 4D-Var error covariance normalization coefficients job script:
#
# This script NEEDS to be run before any run:
#
# (1) It copies a new clean nonlinear model initial conditions
#     file. The nonlinear model is initialized from the
#     background or reference state.
# (2) Specify model, initial conditions, boundary conditions, and
#     surface forcing error covariance input standard deviations
#     files.
# (3) Specify model, initial conditions, boundary conditions, and
#     surface forcing error covariance input/output normalization
#     factors filenames.
# (4) Create 4D-Var input script "c4dvar.in" from a template and
#     specify the error covariance standard deviation, and error
#     covariance normalization factors files to be used.
#
#####
#
# Set path definition to one directory up in the tree.
```

Compile: build_roms.csh

1. Set a local environmental variable to define the path to the directories where all this project's files are kept.

```
setenv MY_ROOT_DIR      ${HOME}/ocean/toms/repository  
setenv MY_PROJECT_DIR   ${PWD}
```

2. Location of your ROMS source code.

```
setenv MY_ROMS_SRC      ${MY_ROOT_DIR}/trunk
```

3. Path of Makefile configuration (*.mk) files

```
setenv COMPILERS        ${MY_ROMS_SRC}/Compilers  
setenv COMPILERS        ${HOME}/Compilers/ROMS
```

4. Build script invoked CPP options.

```
setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DNORMALIZATION"  
setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DANA_initial"  
setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DANA_SPONGE"  
  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DADJUST_BOUNDARY"  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DADJUST_WSTRESS"  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DADJUST_STFLUX"  
  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DBALANCE_OPERATOR"  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DZETA_ELLIPTIC"  
  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DCOLLECT_ALLREDUCE"  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DRIDGE_ALLGATHER"  
  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DDEBUGGING"  
#setenv MY_CPP_FLAGS    "${MY_CPP_FLAGS} -DPOSITIVE_ZERO"
```

5. Compiler selection environment variables.

```
setenv USE_MPI          on  
setenv USE_MPIF90       on  
setenv which_MPI        openmp  
  
setenv FORT             ifort
```

6. Use custom library paths

```
#setenv USE_MY_LIBS no      # use system default library paths  
setenv USE_MY_LIBS yes     # use my customized library paths  
  
set MY_PATHS = ${COMPILERS}/my_build_paths.csh  
  
if ($USE_MY_LIBS == 'yes') then  
  source ${MY_PATHS} ${MY_PATHS}  
endif
```

Build Script: build.csh

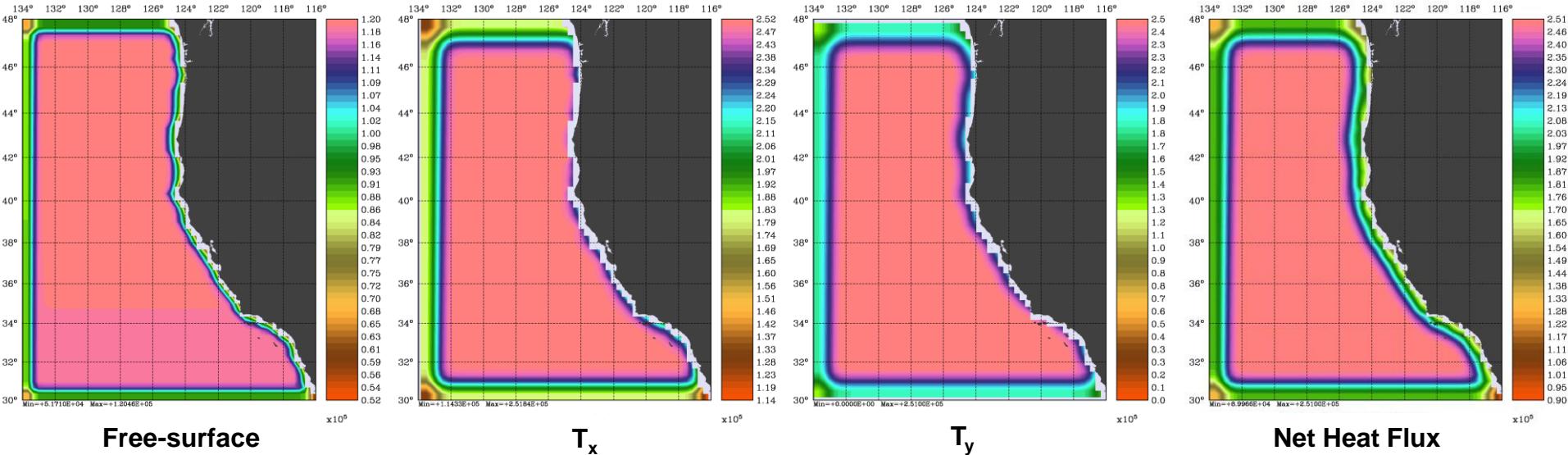
```
#!/bin/csh -f
#
# $Id: build_roms.csh 977 2019-07-26 06:01:07Z arango $
#::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::
# Copyright (c) 2002-2019 The ROMS/TOMS Group :::
# Licensed under a MIT/X style license :::
# See License_ROMS.txt :::
#:::::::::::::::::::::::::::: Hernan G. Arango :::
#
# ROMS/TOMS Compiling CSH Script :::
#
# Script to compile an user application where the application-specific :::
# files are kept separate from the ROMS source code. :::
#
# Q: How/why does this script work? :::
#
# A: The ROMS makefile configures user-defined options with a set of :::
# flags such as ROMS_APPLICATION. Browse the makefile to see these. :::
# If an option in the makefile uses the syntax ?= in setting the :::
# default, this means that make will check whether an environment :::
# variable by that name is set in the shell that calls make. If so :::
# the environment variable value overrides the default (and the :::
# user need not maintain separate makefiles, or frequently edit :::
# the makefile, to run separate applications). :::
#
# Usage: :::
#       ./build_roms.csh [options] :::
#       ... :::
```

Build Script: **my_build_paths.csh**

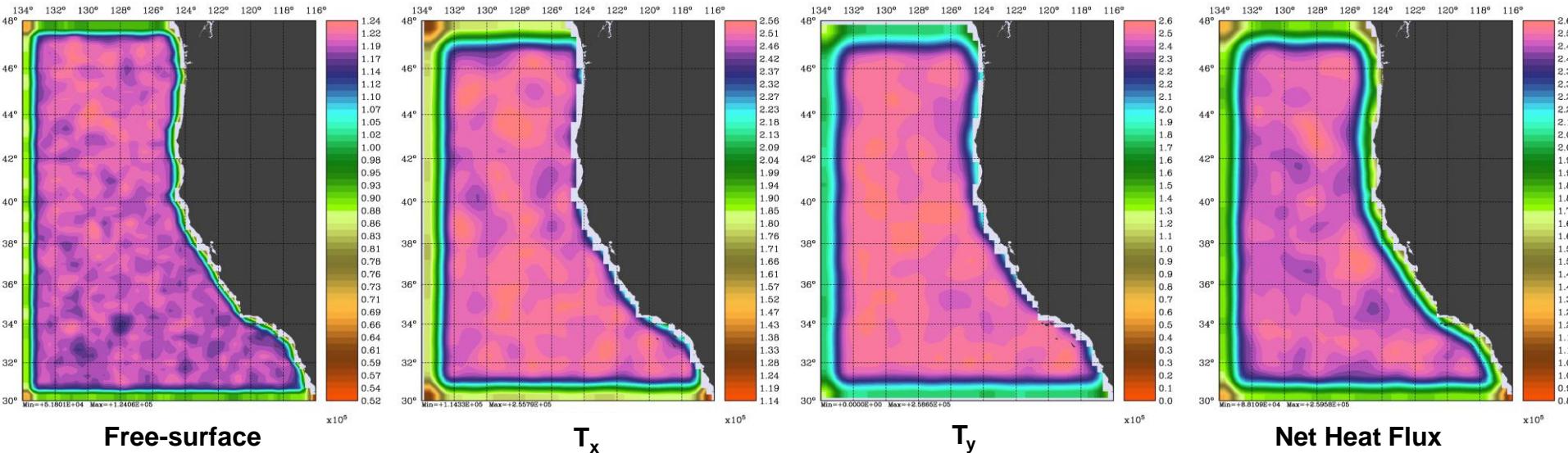
```
# svn $Id$  
#:::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::::  
# Copyright (c) 2002-2019 The ROMS/TOMS Group :::  
# Licensed under a MIT/X style license :::  
# See License_ROMS.txt :::  
#:::::::::::::::::::::::::::: Hernan G. Arango :::  
#  
# ROMS/TOMS Customized Compiling Libraries Script :::  
#  
# This C-shell script sets the customized library paths needed by the :::  
# build script when the environmental variable USE_MY_LIBS has a 'yes' :::  
# value. :::  
#  
# For example, in build_roms.csh we have: :::  
#  
#     if ($USE_MY_LIBS == 'yes') then :::  
#         source ${COMPILERS}/my_build_paths.csh :::  
#     endif :::  
#:::::::::::::::::::::::::::::::::::::::::::::::::  
  
set separator = `perl -e "print ':' x 100;"`  
  
echo ""  
echo "${separator}"  
echo "Using customized library paths from:  $1"  
echo "${separator}"  
echo ""  
  
#-----  
#-----
```

Error Covariance Normalization Coefficients

EXACT

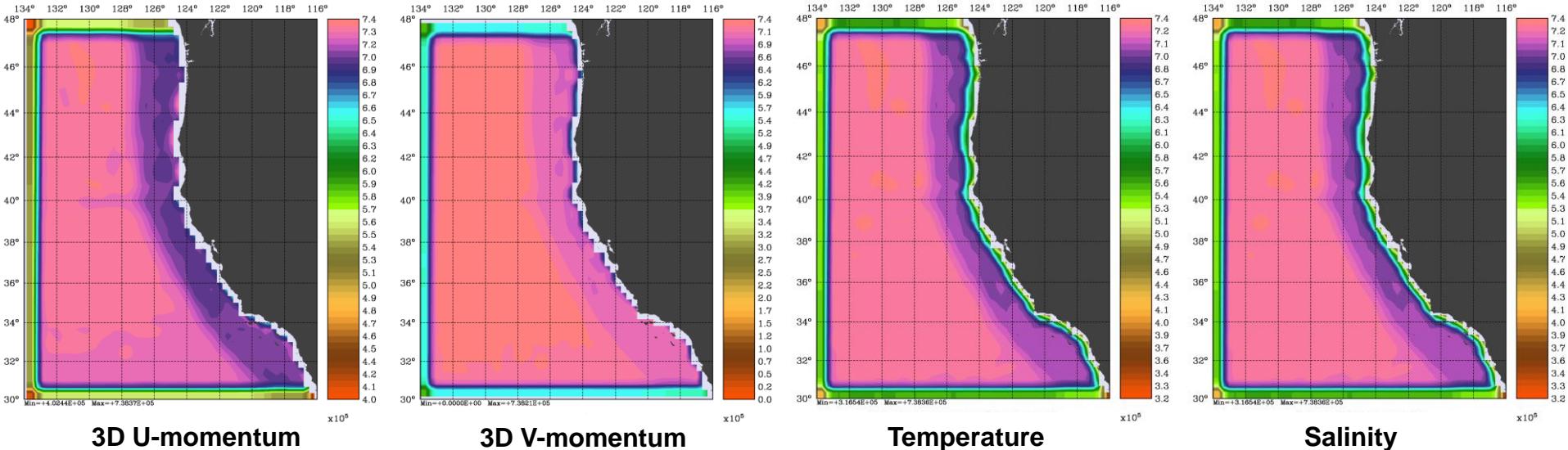


RANDOMIZATION

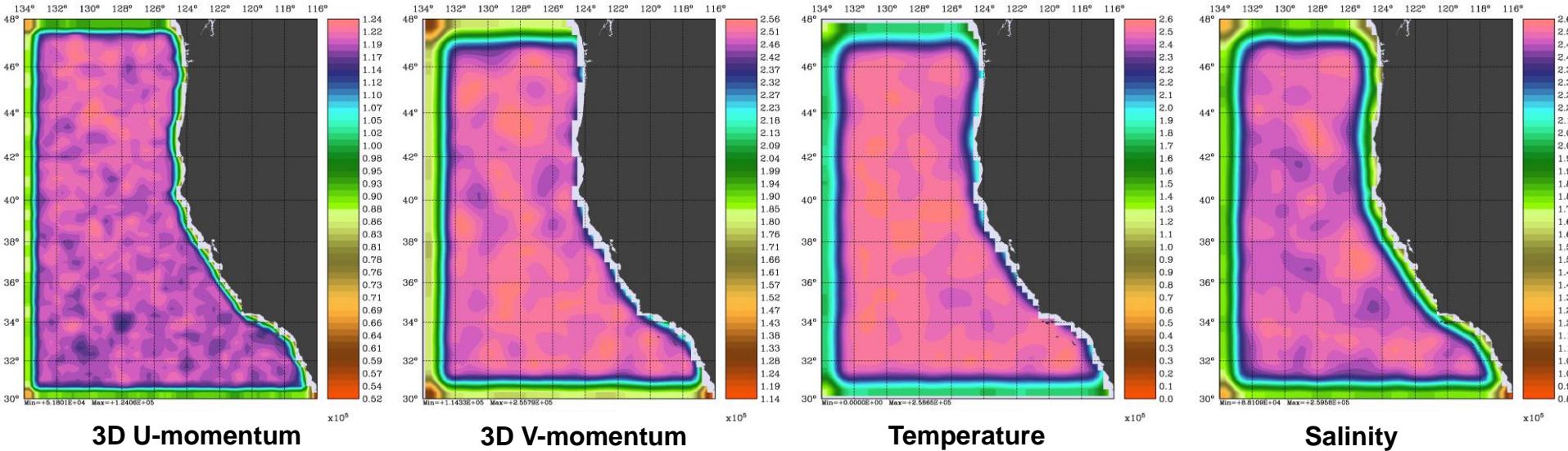


Error Covariance Normalization Coefficients

EXACT



RANDOMIZATION



References

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